

On the Numerical Range of a Generalized Derivation

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Abstract

We examine the relationship between the numerical range of the restriction of a generalized derivation to a norm ideal J and that of its implementing elements.

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1 Introduction

Given a Banach algebra \mathcal{A} , \mathcal{A}^* the dual of \mathcal{A} , $S(\mathcal{A}) = \{x \in \mathcal{A} : \|x\| = 1\}$, the unit sphere, and $x \in S(\mathcal{A})$, let $D(x, \mathcal{A}) = \{f \in \mathcal{A}^* : f(x) = 1 = \|f\|\}$.

The Hahn-Banach theorem guarantees that $D(x, \mathcal{A})$ is non empty for each $x \in S(\mathcal{A})$. The elements of $D(I, \mathcal{A})$, I , the identity in \mathcal{A} , are called normalized states or simply states.

For $a \in \mathcal{A}$, and $x \in S(\mathcal{A})$, we define $V(x, a, \mathcal{A}) = \{f(ax) : f \in D(x, \mathcal{A})\}$.

The numerical range of a is the set $V(a, \mathcal{A}) = \bigcup \{V(x, a, \mathcal{A}) : x \in S(\mathcal{A})\}$.

Given a Banach space \mathcal{H} , we may consider the Banach algebra $\mathcal{A} = L(\mathcal{H})$ and define the spatial numerical range of A by

$$W(A; L(\mathcal{H})) = \{f(Ax) : f \in \mathcal{H}^*, x \in \mathcal{H}, \text{ and } \|f\| = \|x\| = 1 = f(x)\}$$

We first give some basic properties of the numerical range.

Bonsal [4], has shown that $V(a, \mathcal{A}) = V(I, a, \mathcal{A})$, and for each $a \in \mathcal{A}$, $V(a, \mathcal{A})$ is a compact convex subset of \mathbb{C} .

Lemma 1. $V(x, a, \mathcal{A}) = \{f(ax) : f \in D(x, \mathcal{A})\}$ is convex.

Proof. Let $\lambda_1, \lambda_2 \in V(x, a, \mathcal{A})$. Then there exist support functionals $f_1, f_2 \in D(x, \mathcal{A})$ such that $\lambda_1 = f_1(ax)$, $\lambda_2 = f_2(ax)$.

Define f on $D(x, \mathcal{A})$ by $f(ax) = tf_1(ax) + (1-t)f_2(ax)$, $t \in (0, 1)$. We need to show that $f \in D(I, \mathcal{A})$. Clearly f is linear and $|f(ax)| = |tf_1(ax) + (1-t)f_2(ax)| \leq t|f_1(ax)| + (1-t)|f_2(ax)| \leq t\|f_1\|\|ax\| + (1-t)\|f_2\|\|ax\| = \|ax\| \Rightarrow \|f\| \leq 1$.

Also, $f(x) = tf_1(x) + (1-t)f_2(x) = 1$

$$\Rightarrow \|f\| \geq 1$$

Thus $f \in D(I, \mathcal{A})$ which is convex and hence $V(x, a, \mathcal{A})$ is convex. \square

For $a \in \mathcal{A}$, we define the left multiplication operator $L_a : \mathcal{A} \rightarrow \mathcal{A}$ by

$$L_a(x) = ax, \forall x \in \mathcal{A} \text{ and } \|L_a\| = \sup \{\|ax\| : x \in \mathcal{A}, \|x\| \leq 1\}$$

L_a is a linear operator in \mathcal{A} and also a bounded operator since

$$\|L_a\| = \sup \{\|ax\| : x \in \mathcal{A}, \|x\| \leq 1\} \leq \|a\|.$$

$L_a(\mathcal{A})$ will denote the set of all left multiplication operators on the algebra \mathcal{A} as a ranges on \mathcal{A} . This set is a normed algebra.

The algebraic numerical range of $L_a \in L_a(\mathcal{A})$ is the non-empty set:

$$V(L_a; L_a(\mathcal{A})) = \{f(L_a); f \in L_a(\mathcal{A})^*, f(L_e) = 1 = \|f\|\}.$$

Similarly the right multiplication operator for $b \in \mathcal{A}$ is defined as ;

$$R_b : \mathcal{A} \rightarrow \mathcal{A}, x \rightarrow xb$$

We note that $\forall x \in \mathcal{A}$ and fixed $a, b \in \mathcal{A}$, $\Delta_{a,b}(x) = L_a(x) - R_b(x) = ax - xb$, is the generalized derivation induced by $a, b \in \mathcal{A}$.

In [3], it is shown that for any Banach algebra \mathcal{A} , $\|L_a\| = \|a\| = \|R_a\|$ and that $V(a; \mathcal{A}) = V(L_a; L(\mathcal{A})) = V(R_a; L(\mathcal{A}))$, $L(\mathcal{A})$ the algebra of the bounded linear operators on \mathcal{A} .

Lemma 2. For $a \in \mathcal{A}$, $L_a \in L_a(\mathcal{A})$, $\|L_a\| = \|a\| = \|R_a\|$

Proof.

$$\begin{aligned} \|L_a\| &= \sup \{ \|L_a(x)\| : \|x\| = 1 \} \\ &= \sup \{ \|ax\| : \|x\| = 1 \} \\ &\leq \|a\| \|x\| \\ &\Rightarrow \|L_a\| \leq \|a\| \dots\dots\dots(i) \end{aligned}$$

If \mathcal{A} has unit e , we have $L_a(e) = ae = a$ which implies $\|a\| = \|L_a(e)\| \leq \|L_a\| \|e\| = \|L_a\| \Rightarrow \|L_a\| \geq \|a\| \dots\dots\dots(ii)$

From (i) and (ii) equality follows.

Similarly we obtain $\|R_a\| = \|a\|$. □

Lemma 3. For $a \in \mathcal{A}$, $V(a; \mathcal{A}) = V(L_a; L(\mathcal{A})) = V(R_a; L(\mathcal{A}))$

Proof. Let $\lambda \in V(a; \mathcal{A})$, Then there exist $f \in S(\mathcal{A})$ such that $f(a) = \lambda$

Now define F on $L(\mathcal{A})$ by

$$F(L_a) = f(ax), \text{ for all } L_a \in L(\mathcal{A}).$$

Clearly F is linear since

$$\begin{aligned} F(\alpha L_a + \beta L_b) &= f(\alpha ax + \beta bx) \\ &= f(\alpha ax) + f(\beta bx) \\ &= \alpha f(ax) + \beta f(bx) \\ &= \alpha F(L_a) + \beta F(L_b), a, b \in \mathcal{A}, \alpha, \beta \in \mathbb{C} \end{aligned}$$

f is also bounded and positive since

$$\|F(L_a)\| = \sup \{ \|f(ax)\| \} \leq \|f\| \|ax\| = c \|L_a\|.$$

Also $F(L_e) = f(ex) = f(x) = 1$ and $\|F\| = 1$.

So F as defined is a positive linear functional on \mathcal{A} .

Take a finite rank operator $b \in L(\mathcal{A})$ defined by

$$bx = g(x)a, \text{ for all } x \in \mathcal{A}, g \in S(\mathcal{A}). \text{ Clearly } \|b\| = 1 \text{ and } F(b) = f(bx) = f(g(x)a) = g(x)f(a) = \lambda. \text{ Hence } V(a; \mathcal{A}) \subseteq V(L_a; L(\mathcal{A}))$$

Conversely we show that $V(L_a; L(\mathcal{A})) \subseteq V(a; \mathcal{A})$

Let $\lambda \in V(L_a; L(\mathcal{A}))$. Then there exists a state $f \in L(\mathcal{A})^*$ such that $f(L_a) = \lambda$

Define a functional $h \in \mathcal{A}^*$ by $h(a) = f(L_a)$. Then :

$$\begin{aligned} h(\alpha a + \beta b) &= f(\alpha L_a + \beta L_b) \\ &= f(\alpha L_a) + f(\beta L_b) \\ &= \alpha f(L_a) + \beta f(L_b) \\ &= \alpha h(a) + \beta h(b) \end{aligned}$$

$\Rightarrow h$ is linear and bounded. h is also positive since $h(a^*a) = f(L_a^*L_a) \geq 0$
 Furthermore h is of norm 1 since $h(e) = f(L_e) = 1$ and
 $1 = |h(e)| \leq \|h\| \|e\| \Rightarrow \|h\| \geq 1$. We also have

$$\begin{aligned} \|h\| &= \sup \{ |h(a)| : \|a\| = 1 \} \\ &= \sup \{ |f(L_a)| : \|L_a\| = 1 \} \\ &\leq \|f\| \\ &= 1 \end{aligned}$$

Thus h is a state on \mathcal{A}^* and so $V(L_a; L(\mathcal{A})) \subseteq V(a; \mathcal{A})$ □

2 NORM IDEALS

Let X and Y be Banach algebras. $L(X)$ and $L(Y)$, the algebra of all bounded linear operators on X and Y respectively.

Let $(J, \|\cdot\|_J)$ be a norm ideal on $L(Y, X)$, the algebra of all bounded linear operator from Y to X such that:

- i) $(J, \|\cdot\|_J)$ is a Banach space
- ii) If $A \in L(X), T \in J, B \in L(Y)$ then $ATB \in J$, and $\|ATB\|_J \leq \|A\| \|T\|_J \|B\|$
- iii) $\|T\| \leq \|T\|_J, T \in J$ and
- iv) $\|T\|_J = \|T\|$, for T a rank- one operator.

If $A \in L(X), B \in L(Y)$ and $T \in J$, then the operators L_A, R_B and $L_A - R_B$ are all bounded linear operators on $L(J)$, the space of all bounded linear operators from J to J , where:

$L_A T = AT$, the left multiplication operator,

$R_B T = TB$, the right multiplication operator and

$(L_A - R_B) T = AT - TB$, the generalized derivation. The following lemma will hold.

Lemma 4. $V(A : L(X)) = V(L_A : L(J))$

Proof. Let $\lambda \in V(A : L(X))$. Then there exist $f \in L(X)^*$ such that

$\lambda = f(A)$, and, $f(I_{L(X)}) = 1 = \|f\|$

Let $\mathcal{A}_0 = \{L_A : A \in L(X), L_A(T) = AT, T \in J\} \subseteq L(J)$.

\mathcal{A}_0 is a linear subspace of $L(X)$.

On \mathcal{A}_0^* , define a linear functional g such that $g(L_A) = f(A)$. Clearly g as defined is a state and the Hahn-Banach theorem guarantees the existence of its extension on $L(J)$. Hence, $V(A : L(X)) \subseteq V(L_A : L(J))$

\Leftarrow : suppose $\lambda \in V(L_A : L(J))$. Then $\exists f \in L(J)^*$ such that $f(L_A) = \lambda$ and

$$f(I_{L(J)}) = 1 = \|f\|.$$

Define a linear operator h on $L(X)^*$ by $h(A) = f(L_A)$. Then $h(I) = f(I_{L(J)}) = 1$.

h is thus a state on $L(X)^*$ and $V(L_A : L(J)) \subseteq V(A : L(X))$ □

3 Norm of L_A and R_B in $(J, \|\cdot\|_J)$

Lemma 5. $\|L_A\|_J = \|A\|$

Proof. Condition (ii) above on the definition of a norm ideal implies that L_A and R_B are bounded linear operators on $(J, \|\cdot\|_J)$ and

$$\begin{aligned} \|L_A\|_J &= \text{Sup} \{ \|AX\| : \|X\|_J = 1, X \in J \} \\ &\leq \|A\| \|X\|_J \\ &= \|A\| \end{aligned}$$

Condition (iii) implies $\|L_A\|_J \geq \|A\|$.

It therefore follows that $\|L_A\|_J = \|A\|$

Similarly $\|R_B\|_J = \|B\|$ □

4 Numerical range of the generalized derivation in the norm ideal J

In the past, generalized derivations, their properties and their restrictions to norm ideals have been investigated by many authors. For example, their spectra have been characterized in [7] and [8]. The famous results on the norms of inner derivation and the generalized derivation as obtained by Stampfli [6] using maximal numerical range have ever since provided a crucial lead in defining of norms of elementary operators. We recall the works of Kyle [9] who examines the relationship between the numerical range of an inner derivation, and that of its implementing element.

In his paper, Magajna [2] gives the essential numerical range of the the generalized derivation defined on the Hilbert-Schmidt class in terms of the numerical and the essential numerical ranges of the implementing operators. Shaw [10] in particular, established that the algebra numerical range of a generalized derivation restricted to a norm ideal J is equal to the difference of the algebra numerical ranges of the implementing operators provided that J contains all finite rank operators and is suitably normed. With slight modification we obtain an alternative proof to Shaw's result.

Lemma 6. *Let J be as defined above. Then for $A \in L(X), B \in L(Y), V(\Delta_{A,B} : L(J)) = V(A : L(X)) - V(B : L(Y))$*

Proof. Let $\lambda \in V(\Delta_{A,B}; L(J))$. This implies there exist $f \in L(J)^*$ such that $f(\Delta_{A,B}) = \lambda$ and $f(I_{L(J)}) = 1 = \|f\|$
 Let $\mathcal{A}_0 = \{L_A : A \in L(X), L_A(T) = AT, T \in J\} \subseteq L(J)$ and
 $\mathcal{A}_1 = \{R_B : B \in L(Y), R_B(T) = TB, T \in J\} \subseteq L(J)$ i.e. the set of the left and right multiplication operators respectively in $L(J)$. These are linear subspaces of $L(X)$ and $L(Y)$ respectively. Let also $S(L(J)) = \{f \in L(J)^* : f(I_{L(J)}) = 1 = \|f\|\}$

$$\begin{aligned} \lambda &= f(\Delta_{A,B}; L(J)) = \{f(L_A - R_B : f \in S(L(J)))\} \\ &= \{f(L_A) : f \in L(X)^*, f(I_{L(X)}) = 1 = \|f\|\} \\ &\quad - \{f(R_B) : f \in L(Y)^*, f(I_{L(Y)}) = 1 = \|f\|\} \\ &= V(L_A : L_A \in L(J)) - V(R_B : R_B \in L(J)) \\ &\in V(A : L(X)) - V(B : L(Y)) \end{aligned}$$

To prove the reverse inclusion, we make use of the spatial numerical range. Choose λ in $W(A : L(X))$ and μ in $W(B : L(Y))$. Then we can find functionals f and g in $L(X)^*, L(Y)^*$ such that

$$\|f\| = \|x\| = f(x) = 1, \text{ with } f(Ax) = \lambda \text{ and}$$

$$\|g\| = \|y\| = g(y) = 1, \text{ with } g(By) = \mu$$

Let X be a rank one operator in J such that $Xz = g(z)x, \forall z \in Y$,

Also define F in $L(J)^*$ by $F(T) = f(Ty), \forall T \in L(J)$

Then $F(X) = f(Xy) = fg(y)x = g(y)f(x) = 1$,

$F(I) = f(Iy) = fg(y)x = g(y)f(x) = 1$ and

$$|F(T)| \leq \|f\| \|T\|_J \|Y\| = \|T\|_J$$

Clearly $\|F\|_J = \|X\|_J = 1$ and $(I_{L(J)}, F) \in L(J) \times L(J)^*$

Thus,

$$\begin{aligned} F(\Delta_{A,B}(X)) &= F(AX - XB) \\ &= f(AX - XB)y \\ &= f(AXy) - f(XBy) \\ &= f(g(y)Ax) - f(g(y)Bx) \\ &= f(Ax)g(y) - f(x)g(By) \\ &= \lambda - \mu \\ &\in \{W(A : L(X)) - W(B : L(Y))\} \end{aligned}$$

Now

$$\begin{aligned} V(\Delta_{A,B}; L(J)) &= \overline{\text{co}}W(\Delta_{A,B}; L(J)) \\ &\supseteq \overline{\text{co}}\{W(A; L(X)) - W(B; L(Y))\} \\ &= \overline{\text{co}}\{W(A; L(X))\} - \overline{\text{co}}\{W(B; L(Y))\} \\ &= V(A; L(X)) - V(B; L(Y)) \end{aligned}$$

Thus $\{V(A; L(X)) - V(B; L(Y))\} \subseteq V(\Delta_{A,B}; L(J))$ \square

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